

# Package ‘leidenbase’

April 2, 2025

**Type** Package

**Title** R and C/C++ Wrappers to Run the Leiden find\_partition() Function

**Version** 0.1.35

**Description** An R to C/C++ interface that runs the Leiden community detection algorithm to find a basic partition (). It runs the equivalent of the 'leidenalg' find\_partition() function, which is given in the 'leidenalg' distribution file 'leiden/src/functions.py'. This package includes the required source code files from the official 'leidenalg' distribution and functions from the R 'igraph' package. The 'leidenalg' distribution is available from <<https://github.com/vtraag/leidenalg/>> and the R 'igraph' package is available from <<https://igraph.org/r/>>. The Leiden algorithm is described in the article by Traag et al. (2019) <[doi:10.1038/s41598-019-41695-z](https://doi.org/10.1038/s41598-019-41695-z)>. Leidenbase includes code from the packages: igraph version 0.9.8 with license GPL (>= 2), leidenalg version 0.8.10 with license GPL 3.

**Imports** igraph (>= 0.9.0)

**License** GPL-3

**Encoding** UTF-8

**RoxygenNote** 7.3.1

**Depends** R (>= 3.5.0)

**Suggests** rmarkdown, knitr, testthat (>= 3.1.0), pandoc

**URL** <https://github.com/cole-trapnell-lab/leidenbase>

**BugReports** <https://github.com/cole-trapnell-lab/leidenbase/issues>

**NeedsCompilation** yes

**Maintainer** Brent Ewing <bge@uw.edu>

**VignetteBuilder** knitr

**Author** Brent Ewing [aut, cre],  
 Vincent Traag [ctb],  
 Gábor Csárdi [ctb],  
 Tamás Nepusz [ctb],  
 Szabolcs Horvat [ctb],  
 Fabio Zanini [ctb]

**Repository** CRAN

**Date/Publication** 2025-04-02 17:50:02 UTC

## Contents

leiden_find_partition . . . . .	2
<b>Index</b>	<b>5</b>

---

leiden\_find\_partition *Leiden find partition community detection function*

---

### Description

R to C wrapper that runs the basic Leiden community detection algorithm, which is similar to the `find_partition()` function in the python Leidenalg distribution.

### Usage

```
leiden_find_partition(
  igraph,
  partition_type = c("CPMVertexPartition", "ModularityVertexPartition",
    "RBConfigurationVertexPartition", "RBERVertexPartition",
    "SignificanceVertexPartition", "SurpriseVertexPartition"),
  initial_membership = NULL,
  edge_weights = NULL,
  node_sizes = NULL,
  seed = NULL,
  resolution_parameter = 0.1,
  num_iter = 2,
  verbose = FALSE
)
```

### Arguments

<code>igraph</code>	R igraph graph.
<code>partition_type</code>	String partition type name. Default is CPMVertexPartition.
<code>initial_membership</code>	Numeric vector of initial membership assignments of nodes. These are 1-based indices. Default is one community per node.

<code>edge_weights</code>	Numeric vector of edge weights. Default is 1.0 for all edges.
<code>node_sizes</code>	Numeric vector of node sizes. Default is 1 for all nodes.
<code>seed</code>	Numeric random number generator seed. The seed value must be either NULL for random seed values or greater than 0 for a fixed seed value. Default is NULL.
<code>resolution_parameter</code>	Numeric resolution parameter. The value must be greater than 0.0. Default is 0.1. The resolution_parameter is ignored for the partition_types ModularityVertexPartition, SignificanceVertexPartition, and SurpriseVertexPartition.
<code>num_iter</code>	Numeric number of iterations. Default is 2.
<code>verbose</code>	A logic flag to determine whether or not we should print run diagnostics.

## Details

The Leiden algorithm is described in From Louvain to Leiden: guaranteeing well-connected communities. V. A. Traag and L. Waltman and N. J. van Eck Scientific Reports, 9(1) (2019) DOI: 10.1038/s41598-019-41695-z.

Significance is described in Significant Scales in Community Structure V. A. Traag, G. Krings, and P. Van Dooren Scientific Reports, 3(1) (2013) DOI: 10.1038/srep02930

Notes excerpted from leidenalg/src/VertexPartition.py

- *CPMVertexPartition* Implements Constant Potts Model. This quality function uses a linear resolution parameter and is well-defined for both positive and negative edge weights.
- *ModularityVertexPartition* Implements modularity. This quality function is well-defined only for positive edge weights.
- *RBCConfigurationVertexPartition* Implements Reichardt and Bornholdt's Potts model with a configuration null model. This quality function uses a linear resolution parameter and is well-defined only for positive edge weights.
- *RBERVertexPartition* Implements Reichardt and Bornholdt's Potts model with an Erdos-Renyi null model. This quality function uses a linear resolution parameter and is well-defined only for positive edge weights.
- *SignificanceVertexPartition* Implements Significance. This quality function is well-defined only for unweighted graphs.
- *SurpriseVertexPartition* Implements (asymptotic) Surprise. This quality function is well-defined only for positive edge weights.

## Value

A named list consisting of a numeric vector of the node community memberships (1-based indices), a numeric quality value, a numeric modularity, a numeric significance, a numeric vector of edge weights within each community, a numeric vector of edge weights from each community, a numeric vector of edge weights to each community, and total edge weight in the graph.

## References

V. A. Traag, L. Waltman, N. J. van Eck (2019). From Louvain to Leiden: guaranteeing well-connected communities. *Scientific Reports*, 9(1). DOI: 10.1038/s41598-019-41695-z

Significant Scales in Community Structure V. A. Traag, G. Krings, and P. Van Dooren Scientific Reports, 3(1) (2013) DOI: 10.1038/srep02930

## Examples

# **Index**

`leiden_find_partition, 2`