

Package ‘RegKink’

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Type Package

Version 0.1.0

Title Regression Kink with a Time-Varying Threshold

Description An algorithm is proposed to estimate regression kink model proposed by the paper, Lixiong Yang and Jen-Je Su (2018) <[doi:10.1016/j.jimfin.2018.06.002](https://doi.org/10.1016/j.jimfin.2018.06.002)>.

Imports MASS

Depends R (>= 3.5.0)

License GPL

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| | |
|-----------------------|------------------------------------|
| <code>neg.part</code> | <i>negative part of a variable</i> |
|-----------------------|------------------------------------|

Description

This is a function computing the negtive part of a variable.

Usage

```
neg.part(x)
```

Arguments

| | |
|----------------|-----------------------|
| <code>x</code> | A vector of response. |
|----------------|-----------------------|

Value

| | |
|-----------------|----------------------------------|
| <code>ne</code> | The negative part of a variable. |
|-----------------|----------------------------------|

Examples

```
pt1 <- proc.time()
##Simulated data
set.seed(12345)
n=200
x = rnorm(n)
obj <- neg.part(x)

proc.time() - pt1
```

| | |
|-----------------------|------------------------------------|
| <code>pos.part</code> | <i>positive part of a variable</i> |
|-----------------------|------------------------------------|

Description

This is a function computing the positive part of a variable.

Usage

```
pos.part(x)
```

Arguments

| | |
|----------------|-----------------------|
| <code>x</code> | A vector of response. |
|----------------|-----------------------|

Value

ps The positive part of a variable.

Examples

```
pt1 <- proc.time()  
##Simulated data  
set.seed(12345)  
n=200  
x = rnorm(n)  
obj <- pos.part(x)  
  
proc.time() - pt1
```

reg

linear regression

Description

This is a function computing OLS estimates of linear model.

Usage

```
reg(X,y)
```

Arguments

| | |
|---|-----------------------|
| y | A vector of response. |
| X | data matrix |

Value

bols The ols estimates of a linear regression model.

Examples

```
pt1 <- proc.time()  
##Simulated data  
set.seed(12345)  
n=200  
e = rnorm(n)  
X = cbind(1,rnorm(n))  
b0 =c(1,2)  
y = X  
obj <- reg(X,y)  
  
proc.time() - pt1
```

rkt

*Estimation for regression kink with a time-varying threshold***Description**

This is a function estimating regression kink with a time-varying threshold.

Usage

```
rkt(y,x,z,q,r01,r02,r11,r12,stp1,stp2)
```

Arguments

| | |
|------|--|
| y | A vector of response. |
| x | A vector of regressor |
| z | A data matrix of control variables |
| q | A vector of variable affecting threshold |
| r01 | Lower bounder of parameter space for r0 |
| r02 | Upper bounder of parameter space for r0 |
| r11 | Lower bounder of parameter space for r1 |
| r12 | Upper bounder of parameter space for r1 |
| stp1 | Step used in grid search of r0 |
| stp2 | Step used in grid search of r1 |

Value

A list with the elements

| | |
|-----------|--|
| bols | The OLS estimates when a kink effect is ignored. |
| bt | The regression coefficients when a kink effect is included in the model. |
| gammahat0 | The estimated threshold of the constant one in threshold parameters. |
| gammahat1 | The estimated threshold of the slop in threshold parameters. |
| sig | The sum of squared errors of the kink model. |

Examples

```
sta <- proc.time()
##Simulated data
set.seed(12345)
n=200
x = rnorm(n)
q = rnorm(n)
rt = 0.2 - 0.5*q
z = rnorm(n)
```

```
x1 = cbind(neg.part(x-rt),pos.part(x-rt),z)
b0 =c(1,2,1)
y = b0[1]*x1[,1]+b0[2]*x1[,2]+b0[3]*x1[,3]+ rnorm(n)

# set grid search paramaters
r01 = 0
r02 = 2
stp1 = 0.1
r11 = -10
r12 = 5
stp2 = 0.1
# estimate the model with a state-dependent threshold
est1 <- rkt(y,x,z,q,r01,r02,r11,r12,stp1,stp2)

proc.time() - sta
```

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