

# Package ‘ROI.plugin.qpoases’

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**Version** 1.0-3

**Title** 'qpOASES' Plugin for the 'R' Optimization Infrastructure

**Description** Enhances the 'R' Optimization Infrastructure ('ROI') package with the quadratic solver 'qpOASES'. More information about 'qpOASES' can be found at <<https://github.com/coin-or/qpOASES>>.

**Imports** methods, slam, ROI (>= 1.0-0), Rcpp (>= 0.12.11), checkmate

**License** GPL-3

**LinkingTo** Rcpp

**URL** <https://roigrp.gitlab.io>,  
<https://gitlab.com/roigrp/solver/ROI.plugin.qpoases>

**NeedsCompilation** yes

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## Contents

ROI.plugin.qpoases-package	2
Example-1	2

## Index

4

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ROI.plugin.qpoases-package  
*qpOASES*

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## Description

This package provides an interface to qpOASES. pOASES is an open-source C++ implementation of the online active set strategy, which was inspired by important observations from the field of parametric quadratic programming (QP).

## References

- H.J. Ferreau and C. Kirches and A. Potschka and H.G. Bock and M. Diehl. qpOASES: A parametric active-set algorithm for quadratic programming, “Mathematical Programming Computation”, 2014
- H.J. Ferreau and H.G. Bock and M. Diehl. An online active set strategy to overcome the limitations of explicit MPC, “International Journal of Robust and Nonlinear Control”, 2008
- H.J. Ferreau and A. Potschka and C. Kirches. qpOASES “webpage” <https://github.com/coin-or/qpOASES>, 2017

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Example-1

*Quadratic Problem 1*

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## Description

$$\begin{aligned}
 & \text{maximize} \quad x_1^2 + x_2^2 + x_3^2 - 5x_2 \\
 & \text{subject to :} \\
 & -4x_1 - 3x_2 + \geq -8 \\
 & 2x_1 + x_2 + \geq 2 \\
 & -2x_2 + x_3 \geq 0 \\
 & x_1, x_2, x_3 \geq 0
 \end{aligned}$$

## Examples

```

Sys.setenv(ROI_LOAD_PLUGINS = "FALSE")
library("ROI")
library("ROI.plugin.qpoases")

A <- cbind(c(-4, -3, 0),
            c( 2,  1, 0),
            c( 0, -2, 1))
x <- OP(Q_objective(diag(3), L =  c(0, -5, 0)),
        L_constraint(L = t(A),

```

```
dir = rep(">=", 3),
rhs = c(-8, 2, 0))

opt <- ROI_solve(x, solver="qpoases")
opt
## Optimal solution found.
## The objective value is: -2.380952e+00
solution(opt)
## [1] 0.4761905 1.0476190 2.0952381
```

# Index

Example-1, [2](#)

ROI.plugin.qpoases-package, [2](#)